

Exploratory Flutter Test in a Cryogenic Wind Tunnel

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An experimental study to explore the feasibility of conducting flutter tests in cryogenic wind tunnels was conducted in the NASA Langley 0.3-m Transonic Cryogenic Tunnel. The model used consisted of a rigid wing with an integral, flexible beam support that was cantilever mounted from the tunnel wall. The wing had a rectangular planform of aspect ratio 1.5 and a 64A010 airfoil. Various considerations and procedures for conducting flutter tests in a cryogenic wind tunnel were evaluated. Flutter onset conditions were established from extrapolated subcritical response measurements. A flutter boundary was determined at cryogenic temperatures over a Mach number M range of 0.5–0.9. Flutter was obtained at two different Reynolds numbers R at $M=0.5$ ($R=4.4$ and 18.4×10^6) and at $M=0.8$ ($R=5.0$ and 10.4×10^6). Flutter analyses using subsonic lifting surface (kernel function) aerodynamics were made over the range of test conditions. To evaluate the Reynolds number effects at $M=0.5$ and 0.8, the experimental results were adjusted using analytical trends to account for differences in the model test temperatures and mass ratios. The adjusted experimental results indicated that increasing Reynolds number from 5.0 to 20.0×10^6 decreased the dynamic pressure by 4.0–6.5% at $M=0.5$ and 0.8. The Reynolds number effects may possibly be within the scatter band of the experimental measurements.

Nomenclature

| | |
|------------|--|
| A | = response amplitude of subcritical response data peak, V |
| b | = wing semispan, in. |
| b_0 | = half-chord length, in. |
| E | = Young's modulus of elasticity, lb/in. ² |
| f | = frequency, Hz |
| f_F | = flutter frequency, Hz |
| g | = structural damping |
| g_δ | = incremental damping |
| M | = Mach number |
| M_0 | = model mass excluding support shaft, lb·s ² /in. |
| P_t | = stagnation pressure, lb/in. ² |
| q | = dynamic pressure, lb/in. ² |
| q_F | = flutter dynamic pressure, lb/in. ² |
| R | = Reynolds number based on chord |
| T | = temperature, °F |
| T_t | = stagnation temperature, °F or °R |
| V | = velocity, in./s |
| V_F | = flutter velocity, in./s |
| V_I | = flutter speed index = $V/(\omega_0 b_0 \sqrt{\mu})$ |
| ρ | = density, lb·s ² /in. ⁴ |
| μ | = mass ratio = $M_0/(\pi b_0^2 b \rho)$ |
| μ_c | = coefficient of viscosity, lb·s/in. ² |
| ν | = Poisson's ratio |
| ω_0 | = first torsion frequency, rad/s |

Subscripts

| | |
|-----|-----------------------------------|
| a | = analysis result |
| i | = vibration mode order = 1,2,3... |
| m | = measured result |

Introduction

A WORKSHOP was held at the NASA Langley Research Center (LaRC) in 1980 to examine the state of technology in high Reynolds number research. Seven technical panels were assembled at the workshop to plan initial research efforts for the National Transonic Facility (NTF), a cryogenic wind tunnel that is capable of obtaining high Reynolds numbers. One of the studies recommended by the panel on Aeroelasticity and Unsteady Aerodynamics was an exploratory flutter test of a generic wing model to determine the magnitude of possible Reynolds number effects on flutter.¹ As a result of this panel recommendation, the present flutter study was initiated. In this study, an exploratory flutter test was conducted in the 0.3-m Transonic Cryogenic Tunnel (TCT) at the NASA LaRC. The primary objectives of this test were to explore the feasibility of conducting flutter tests in a cryogenic wind tunnel and to develop procedures for such tests. Another objective was to determine if Reynolds number effects could be separated from the effects of other test parameters known to influence flutter and, if so, how significant is the effect of Reynolds number on classical wing flutter (bending-torsion coupling).

The approach used in this study was to design a flutter model that would be both simple to analyze and reasonably safe to test in a cryogenic wind tunnel. A reliable analytical prediction of the flutter boundary was important so that actual, "hard" flutter could be avoided during the test or, at least, approached cautiously. Even so, this test was approached as a high-risk test in the 0.3-m TCT. The present flutter model design consists of a relatively rigid wing mounted on a short integral, rectangular beam flexure, the root of which is clamped to the tunnel wall. The wing was constructed of solid metal with a symmetric airfoil section. The wing planform was rectangular and had a panel aspect ratio of 1.5. The flexure beam was sized to give primary wing bending and torsion frequencies that would permit the wing to flutter at the desired dynamic pressure in the tunnel. With this design, the analysis was simplified because the majority of the flexibility is exhibited in the rectangular beam support, while the aerodynamic forces are generated by the "rigid" wing.

Several special considerations are needed for aeroelastic model testing in a cryogenic wind tunnel. In order to utilize its full Reynolds number and dynamic pressure capabilities, the large temperature range capability of a cryogenic facility

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must be exercised and this causes many changes not normally experienced in conventional wind tunnels. For this reason, ground vibration tests (GVT) were conducted on this cryogenic flutter model throughout the operating temperature range of the 0.3-m TCT before beginning the wind-tunnel test. Results from the GVT were used in the flutter analysis.

In cryogenic tunnels, there are several different operating procedures for approaching the flutter boundary. During the present wind-tunnel test, two tunnel operating procedures were evaluated. The four test parameters considered to have the most significant effects on flutter were temperature (because temperature affects vibration frequencies), mass ratio, Mach number, and Reynolds number. An attempt was made to isolate any Reynolds number effect on flutter by using appropriate test procedures and by using analytical trends to adjust experimental results obtained at a constant Mach number. Presented herein are the results of this study.

Test Apparatus

Wind Tunnel

The 0.3-m TCT² is a closed-circuit, continuous wind tunnel that provides the capability of testing at high Reynolds number by a combination of low temperature and high pressure. The cryogenic temperatures are obtained by injecting liquid nitrogen (-320°F) into the tunnel circuit. The liquid evaporates and the tests are conducted in gaseous nitrogen. The pressure in the tunnel can be varied between about 1-6 atm. The effects of cryogenic temperatures on Reynolds number and other test parameters are shown in Fig. 1.³ Note that the changes shown are for a constant model size, pressure, and Mach number. Reynolds number is

defined as

$$R = \frac{\text{Inertia force}}{\text{Viscous force}} = \frac{\rho V^2 (2b_0)^2}{\mu_c V (2b_0)} = \frac{\rho V (2b_0)}{\mu_c}$$

Based on these relationships (Fig. 1), the net result of lowering the test medium temperature is to cause a large increase in Reynolds number. Also, note that the dynamic pressure is independent of temperature. Therefore, tests can be conducted at high Reynolds numbers with modest dynamic pressures (as compared to an ambient temperature pressure tunnel) and, also, the Reynolds number may be varied while holding the dynamic pressure constant. Furthermore, aeroelastic testing can be conducted at a constant Reynolds number by proper control of pressure and temperature (Fig. 2).

Wind-Tunnel Model

The model consists of a rectangular planform wing supported by an integral, rectangular beam flexure. The beam flexure was clamped to the wind-tunnel turntable. Photographs of the model and sketches giving geometric information are presented in Figs. 3 and 4, respectively. The wing has an aspect ratio of 1.5 and a NACA 64A010 airfoil shape. A semicircular wing tip shape with a diameter equal to the thickness of the wing at a given chord station was used. Also, a circular plate was attached to the wing root as a

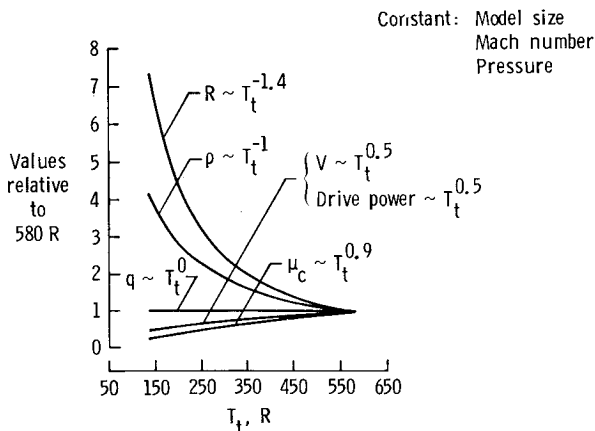


Fig. 1 Temperature variation of tunnel parameters.

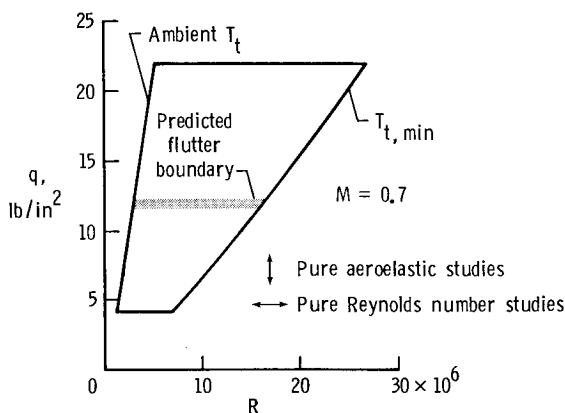
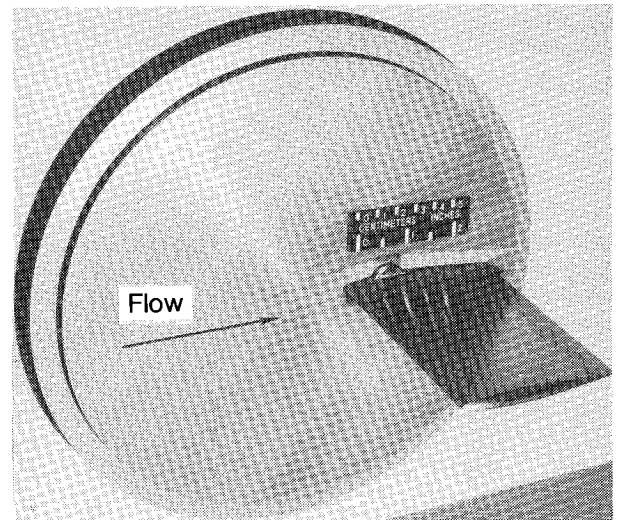
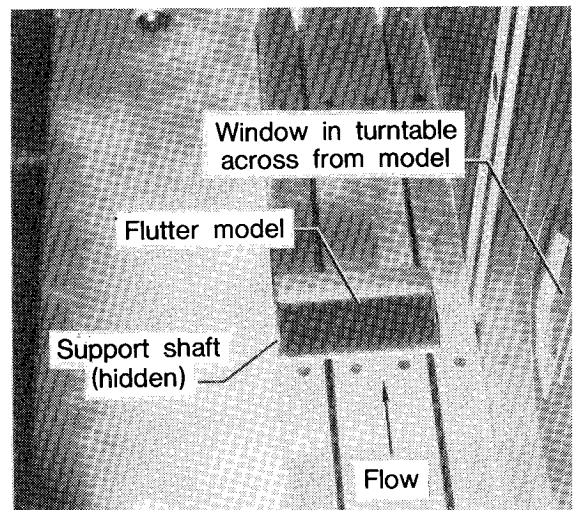


Fig. 2 Operating boundary for the 0.3-m TCT showing two types of experimental studies.



a) Three-quarter side view.



b) Top front view.

Fig. 3 Photographs of model mounted in tunnel.

cover over the support flexure slot in the turntable (see Fig. 3). The flexure is attached to the wing root at the 0.3-chord position (Fig. 4).

Model Material

Cryogenic temperatures eliminate the use of some conventional construction materials because of their undesirable characteristics at low temperatures. An 18 Ni grade 200 maraging steel was chosen as the material for the present flutter model because of its high strength and relatively constant properties over a large temperature range. Figure 5^{4,5} shows that the Young's modulus of elasticity E varies less than 5% and Poisson's ratio ν less than 2% over the temperature operating range of the 0.3-m TCT. Also, the dimensional stability of 18 Ni grade 200 steel with temperature makes it a highly desirable material for transonic airfoils that require extremely close tolerances. An additional advantage of this steel alloy is its high fracture toughness. A flutter model, which is designed primarily by stiffness criteria rather than strength, becomes safer to test when high-strength and high-ductility materials can be used. One undesirable characteristic of high-strength alloys is that the material may fail in a brittle manner if cracks are present, even though the tensile ductility of the material is high.⁴ This is a condition that must be avoided in a flutter model because of the possibility of a brittle fracture occurring as the model undergoes the oscillations normally encountered during flut-

ter testing. No "hard" flutter points were obtained during this test to minimize the risk of such a failure. The high-strength and fracture toughness values of 18 Ni grade 200 steel also decreased the probability of failure.

Instrumentation

The model was instrumented with two strain gage bridges located on the support flexure near the cantilever point and oriented such that the bending and torsional strains were measured. A thermocouple was mounted near the strain gage bridges for monitoring the model temperature. The sensitivity of the strain gage bridges varied by less than 1% over the test temperature range, so no thermal drift corrections were considered necessary. The thermocouple was used to indicate when the temperature of the model support flexure reached equilibrium with time.

Model Mounting System

The test section used for the present test was 8 in. wide which limits sidewall-mounted, three-dimensional models to a maximum semispan of approximately 5 in. A support system was designed that allowed the model support flexure to extend through a rectangular slot in the sidewall turntable so that the tunnel width was better utilized. Two blocks were constructed from 18 Ni grade 200 maraging steel and clamped above and below the support flexure as shown in Fig. 4. The model is aligned by steel pins and clamped by four screws that pull the blocks tight around the support flexure of the model. These blocks are then attached to the plenum side of the aluminum turntable by three screws.

As a special safety feature, four cylindrically shaped Teflon pads were mounted inside the turntable slot near the wing root as shown in Fig. 4. These pads were designed to limit the model's amplitude of deflection and to soften the impact against the flexure if flutter occurred during the test. The gap between the Teflon pads and the support flexure was sized by the ultimate strength of the model support flexure.

During testing, the model was constantly monitored by television through a video camera and a visual record was taped for later review. A movie camera was activated manually only when something of interest occurred.

Test Procedures

Ground Vibration Test

A ground vibration test (GVT) was conducted on the model at temperatures throughout the operating range of the 0.3-m TCT. A cryogenic chamber facility that uses liquid nitrogen to obtain the low-temperature environment was

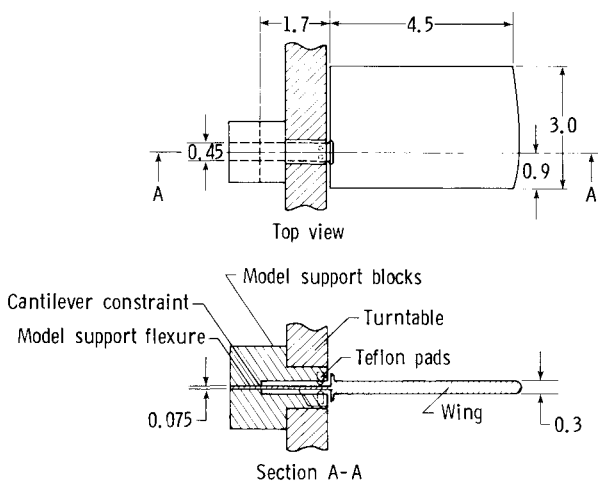


Fig. 4 Sketches of model and support arrangement (dimensions are inches).

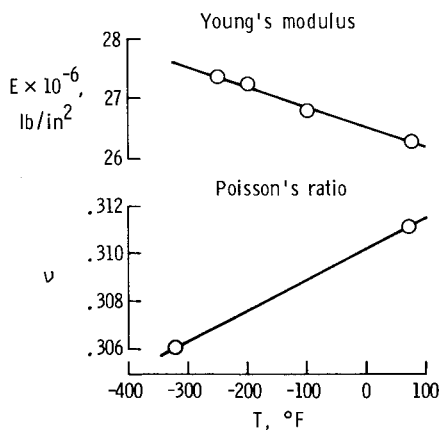


Fig. 5 Temperature variation of some properties of 18 Ni grade 200 steel.

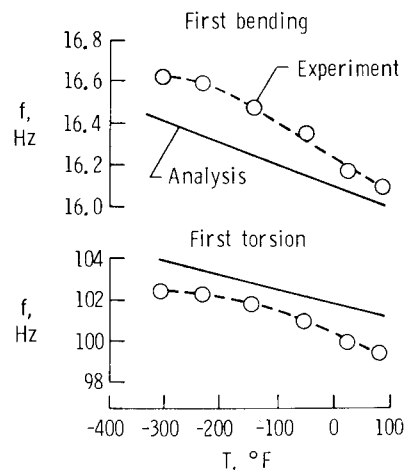


Fig. 6 Some measured and calculated frequencies.

used for the GVT. The flutter model/turntable assembly was mounted to an aluminum backstop in this chamber. Excitation was provided by manually plucking the model with a wooden rod extending through a hole in the bottom of the chamber. In this manner, the model could be excited, usually in either the first bending or the first torsion mode. These are the two modes primarily involved in flutter for this model. Natural frequencies and structural damping were measured for each of these modes. The natural frequencies were obtained from the strain gage responses as monitored by a dynamic signal analyzer. The damping was measured by strain gage signal decay envelopes monitored on a strip chart recorder. The generalized masses and the natural mode shapes for these two modes were also measured at room temperature. These verified the analytical structural dynamic simulations that were used in the flutter analysis. The measured natural frequencies are shown in Table 1 and in Fig. 6. The measured structural damping values are shown in Fig. 7 and measured node lines in Fig. 8. The calculated frequencies and node lines are included in Fig. 8.

Wind-Tunnel Test

Conventionally, flutter tests are conducted by slowly increasing the dynamic pressure until the flutter critical condition is predicted by subcritical response techniques or until flutter actually occurs. Because the goal in cryogenic testing is to determine the Reynolds number effects, operating procedures for conducting tests must allow control of both the Reynolds number and dynamic pressure. The 0.3-m TCT allows independent control of Mach number, temperature, and pressure. Reynolds number is indirectly controlled by proper variation of at least two of these three tunnel conditions. Many combinations of changes in these tunnel parameters can be used in a test. The two tunnel operating procedures that were considered most suitable for flutter model testing were selected for and evaluated in the present test. These procedures are discussed in the following paragraphs.

Constant Mach Number and Reynolds Number

This operating procedure and the resulting variations in the flow parameters are shown in Fig. 9 as procedure 1. Testing at constant Mach number has the advantage of being a relatively safe method of flutter testing. Holding the Reynolds number constant eliminates its possible effects on the aerodynamics and experimental flutter predictions. A disadvantage is that monitoring the changes in stagnation temperature and pressure to keep the Reynolds number constant can become a major task to the project engineer whose major concern is monitoring the model's behavior. This operating procedure is also rather slow; nevertheless, it can be used very successfully. However, the changing material properties with temperature may make this procedure undesirable for flutter testing in some instances.

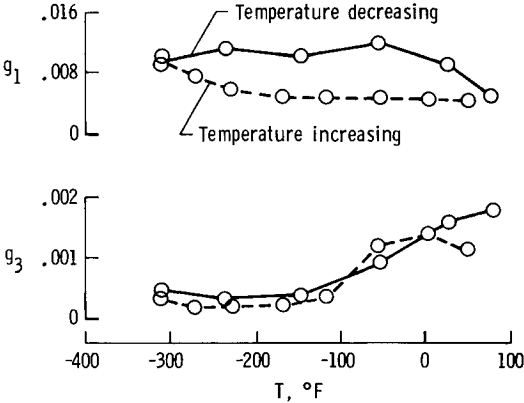


Fig. 7 Measured structural damping values.

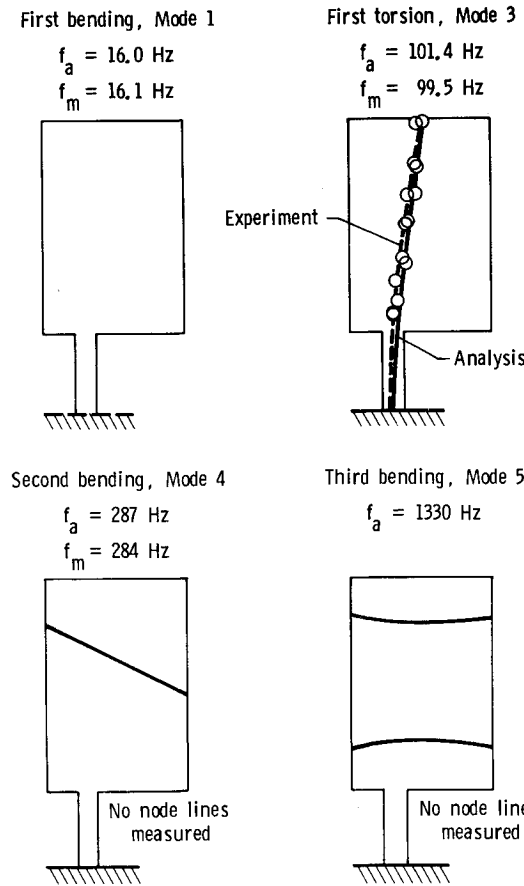
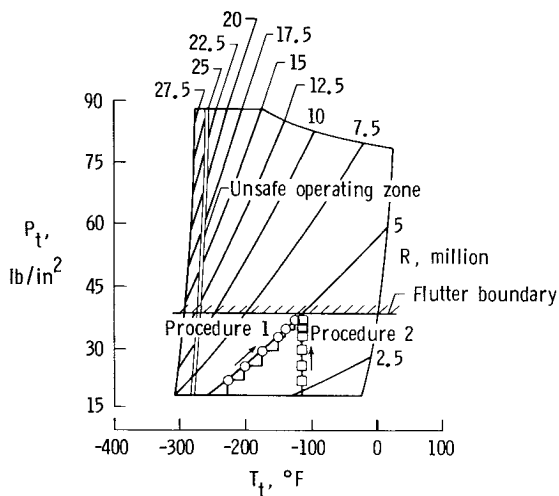


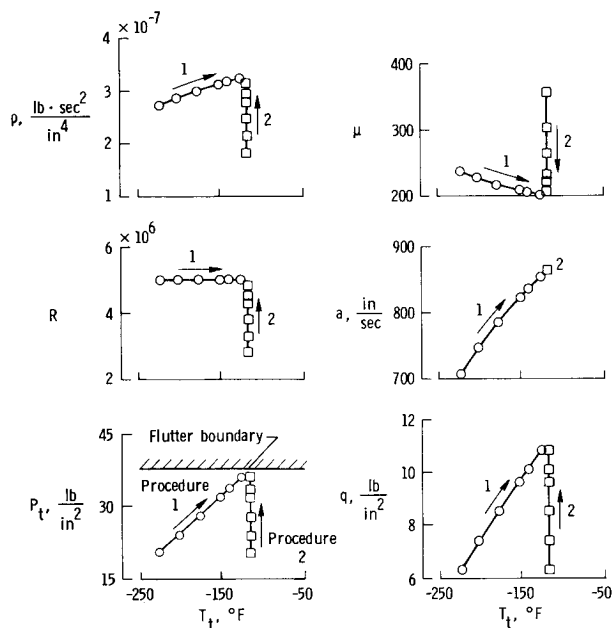
Fig. 8 Node lines and frequencies for the model ($T=81^{\circ}\text{F}$).

Table 1 Calculated and measured natural frequencies at various model temperatures

| Mode | -261°F | | -252°F | | -117°F | | 80.6°F | |
|---------------------|------------|------------|------------|------------|------------|------------|------------|------------|
| | f_a , Hz | f_m , Hz | f_a , Hz | f_m , Hz | f_a , Hz | f_m , Hz | f_a , Hz | f_m , Hz |
| 1 First bending | 16.4 | 16.6 | 16.3 | 16.6 | 16.2 | 16.4 | 16.0 | 16.1 |
| 2 Chordwise bending | 94.6 | — | 94.6 | — | 93.8 | — | 92.6 | 89.0 |
| 3 First torsion | 103.7 | 102.3 | 103.6 | 102.3 | 102.7 | 101.6 | 101.4 | 99.5 |
| 4 Second bending | 293.5 | — | 293.2 | 296 | 290.9 | — | 287.4 | 284 |
| 5 Third bending | 1359 | — | 1358 | — | 1347 | — | 1330 | — |



a) Operating paths on tunnel boundary.



b) Variation of tunnel parameters.

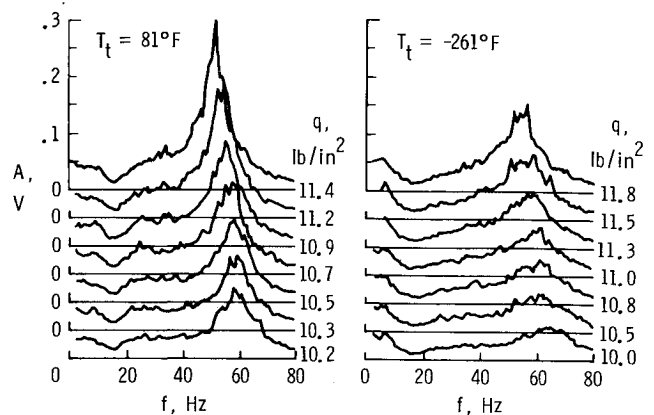
Fig. 9 Operating paths as function of tunnel parameters ($M=0.8$).

Constant Mach Number and Stagnation Temperature

This operating procedure is shown as procedure 2 in Fig. 9. Here, the tunnel operation is relatively easy because only the stagnation pressure must be changed to approach the flutter instability. Because the temperature is held constant, the material properties of the model do not vary during testing. A less desirable consequence is that the Reynolds number is changing as the stagnation pressure is increased. The direct approach to the flutter boundary makes this a relatively safe, and probably the best, procedure for conducting flutter tests. This procedure was used to obtain most of the experimental flutter data in this test.

Subcritical Response Technique

A subcritical response technique, known as the peak-hold method,⁶ was used to predict the onset of flutter during this test. This method involves measuring the maximum response amplitude of a vibration mode for a specific time period at constant dynamic pressure. This measurement is repeated as the dynamic pressure is incrementally increased. Both strain

Fig. 10 Typical subcritical response measurement data ($M=0.5$).

gage bridge outputs were monitored during this test, but the response from the torsion gage gave the most consistent trends and predictions of flutter onset. Some typical measured subcritical response spectra are shown in Fig. 10. At low dynamic pressures, the peaks corresponding to the vibration modes are relatively broad, suggesting that the modes are either well damped or simply not excited by the tunnel turbulence. At conditions near flutter, the response should appear as a distinct, narrow peak indicative of low modal damping. Such "ideal" response data were not generally obtained during this test, but the peak-hold method still gave consistent trends and flutter onset predictions. The response data shown in Fig. 10 at the maximum test dynamic pressure is within 91% of the predicted flutter dynamic pressure for both cases.

Although narrow peaks were not obtained, maximum wide-band responses did occur near frequencies corresponding to the first bending and the first torsion modes. In the peak-hold method, the inverse of the maximum response amplitude is plotted vs dynamic pressure as each measurement is made. As the flutter dynamic pressure is approached, the response amplitude grows infinitely large—at least relative to the response amplitudes at the lower dynamic pressures, so that when the reciprocal of the response is extrapolated to a zero value, the corresponding dynamic pressure required for flutter is established. This can be seen in the peak-hold method plots (Fig. 11) obtained in this test.

The subcritical response measurements (Fig. 10) exhibit another interesting phenomenon. Figure 10 shows response measurements at $M=0.5$ for ambient temperature ($T_t=81^\circ\text{F}$) and for a cryogenic temperature ($T_t=-261^\circ\text{F}$). The temperature level is the major difference between these two measurements. The data were measured on the same day, with the same equipment setup, during consecutive wind-tunnel runs. Yet the response measurement spectra are very different for conditions that are the same percentage removed from the predicted flutter dynamic pressure. The measurements at $T_t=81^\circ\text{F}$ indicate greater model response amplitude and lower damping (more distinct response peaks) than the measurements at $T_t=-261^\circ\text{F}$. This difference in model response is probably due to the reduced power requirement to operate the tunnel at the lower temperature, as shown in Fig. 1. At reduced power, there is less energy in the tunnel flow and, consequently, probably less turbulence to excite the model.

Analytical Predictions

Analyses were made for the model to predict the flutter conditions as a guide for the wind-tunnel test and to separate the effects of Reynolds number on flutter from the effects of mass ratio and temperature changes. Structural dynamic properties of the flutter model were calculated using the engineering analysis language (EAL) finite-element analysis software

Table 2 Calculated model flutter results

| M | T_t , °F | V_F , in./s | q_F , lb/in. ² | V_I | f_F , Hz | μ | $\rho \times 10^6$, lb · s ² /in. ⁴ |
|------|---------------|------------------|--------------------------------|-------|---------------|-------|---|
| 0.5 | -261 | 3912 | 13.72 | 0.67 | 46.7 | 36.7 | 1.79 |
| 0.5 | -252 | 4027 | 13.69 | 0.67 | 46.7 | 38.9 | 1.69 |
| 0.5 | -117 | 5357 | 13.23 | 0.66 | 46.3 | 71.7 | 0.922 |
| 0.5 | 81 | 6780 | 12.56 | 0.66 | 45.2 | 121.0 | 0.546 |
| 0.7 | -261 | 5477 | 12.47 | 0.64 | 41.6 | 79.4 | 0.832 |
| 0.7 | -252 | 5626 | 12.46 | 0.64 | 41.6 | 84.0 | 0.787 |
| 0.7 | -117 | 7361 | 12.16 | 0.62 | 41.1 | 147.2 | 0.449 |
| 0.7 | 81 | 9285 | 11.59 | 0.61 | 40.2 | 245.7 | 0.269 |
| 0.8 | -261 | 6215 | 11.53 | 0.61 | 37.7 | 110.7 | 0.597 |
| 0.8 | -252 | 6371 | 11.53 | 0.61 | 37.7 | 116.3 | 0.568 |
| 0.8 | -117 | 8306 | 11.26 | 0.60 | 37.4 | 202.7 | 0.326 |
| 0.8 | 81 | 10470 | 10.75 | 0.59 | 36.6 | 337.2 | 0.196 |
| 0.85 | -261 | 6570 | 10.87 | 0.60 | 35.3 | 131.4 | 0.503 |
| 0.85 | -252 | 6734 | 10.86 | 0.60 | 35.3 | 138.0 | 0.479 |
| 0.85 | -117 | 8764 | 10.62 | 0.58 | 35.0 | 238.6 | 0.277 |
| 0.85 | 81 | 11045 | 10.15 | 0.58 | 34.2 | 398.1 | 0.166 |
| 0.9 | -261 | 6923 | 9.96 | 0.58 | 32.3 | 158.9 | 0.416 |
| 0.9 | -252 | 7093 | 9.96 | 0.58 | 32.3 | 166.9 | 0.395 |
| 0.9 | -117 | 9214 | 9.74 | 0.57 | 32.0 | 288.6 | 0.229 |
| 0.9 | 81 | 11606 | 9.31 | 0.58 | 31.4 | 478.9 | 0.138 |

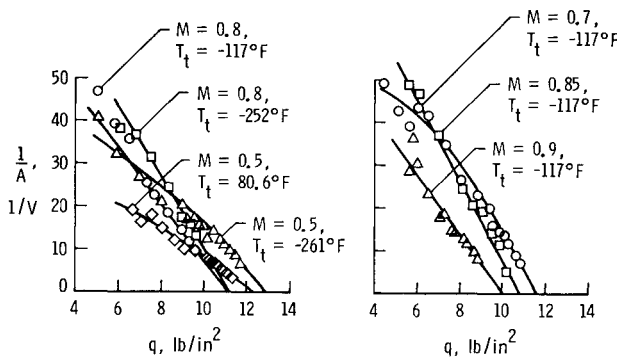


Fig. 11 Test peak-hold plots.

system.⁷ The finite-element model used two-dimensional plate elements as shown in Fig. 12. EAL was used to calculate natural mode shapes, natural frequencies, and generalized masses for the flutter model (Table 1 and Figs. 6 and 8). These analytical results were compared to characteristics obtained in the GVT for the flutter model. Flutter analysis was then conducted using experimentally determined properties or calculated properties if measured values were not available. A flutter analysis software system, known as FAST,⁸ was used to calculate the flutter instability condition. FAST calculates the flutter solution by the k method using aerodynamics obtained through subsonic kernel function lifting surface theory. A typical analysis result showing frequency and damping vs the flutter speed index is shown in Fig. 13. Flutter results were obtained for $M=0.5, 0.7, 0.8, 0.85$, and 0.9 and are presented in Table 2.

Mass Ratio Effects

Prior to this test, it was realized that mass ratio could possibly have a strong effect on flutter because of the large variation in fluid density that occurs during cryogenic testing. Reference 9 has suggested that it is possible to conduct cryogenic flutter tests at several Reynolds numbers, while avoiding the mass ratio effects by using models constructed from different materials. Because only one model was built for this test, analytical results were used to account for the effects of the mass ratio on flutter. An example flut-

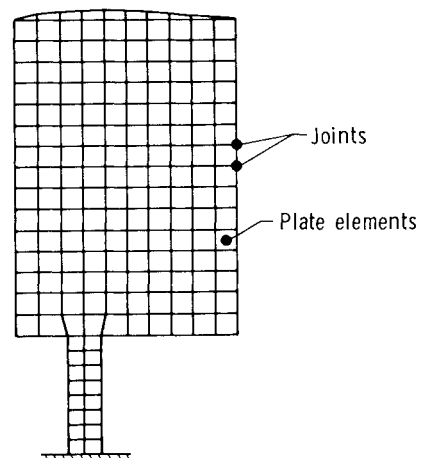


Fig. 12 Finite-element simulation of model.

ter analysis calculation for this model is shown in Fig. 14. This figure shows the fluid density that must be attained to induce flutter for a constant Mach number and a given velocity. (For this example, the analysis solution assumed material properties that were independent of temperature.) For a conventional wind tunnel, temperature is virtually constant so that there is a specific velocity associated with each Mach number and, therefore, only one density associated with a flutter solution, as can be seen in the figure. This density and velocity are known as the "matched point" conditions. In a cryogenic wind tunnel, multiple matched-point conditions are possible because of the variation in velocity due to changes in the temperature. The range of matched point conditions for the temperatures attainable in the 0.3-m TCT is shown in Fig. 14. The velocity vs density plot was transformed into a plot of dynamic pressure vs mass ratio as shown in Fig. 15. It was then used to determine the percentage dynamic pressure correction between the actual test mass ratio values. This was the procedure used to adjust the experimental flutter dynamic pressures for mass ratio effects. The predicted effects of the mass ratio on flutter were found to be fairly small for the range of test mass ratios. At $M=0.5$, analysis predicted a 2.9% increase in the flutter

dynamic pressure as the mass ratio decreased from 119.0 to 38.7 (at a constant temperature). (These values of mass ratio correspond to the experimental values discussed later in this paper and shown in Table 3.)

Temperature Effects

Analysis was also conducted to predict the effect of the temperature variation on flutter. Measured structural properties at the specified temperature conditions that covered the test range were used in the analysis. This analysis was conducted at a constant mass ratio corresponding to the lowest Reynolds number experimental data point. The effect of temperature on flutter as predicted by analysis can be seen in Fig. 15. As indicated in the figure, decreasing temperature results in increasing the flutter dynamic pressure. This is attributed to the increasing model stiffness reflecting the elastic moduli changes as the temperature decreases. At $M=0.5$, analytically decreasing the temperature from 81 to -261°F (corresponding to the experimental data in Table 3) increases the flutter dynamic pressure 5.6%.

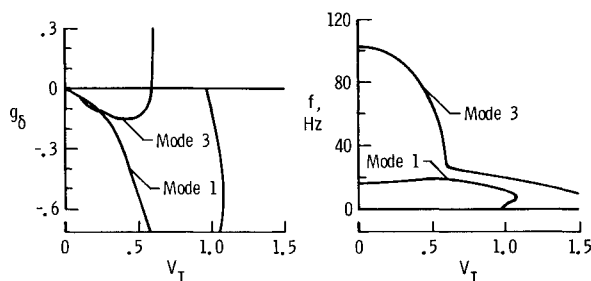


Fig. 13 Typical calculated flutter results.

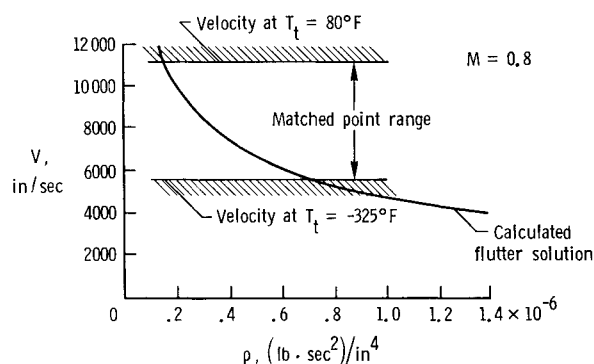


Fig. 14 Calculated flutter solution showing the matched point range in the 0.3-m TCT.

Table 3 Experimental flutter results

| M | T_t , $^\circ\text{F}$ | V_F , in./s | q_F , lb/in. ² | V_I | f_F , Hz | μ | $\rho \times 10^6$, lb·s ² /in. ⁴ | $R \times 10^{-6}$ |
|------|-----------------------------|------------------|--------------------------------|-------|---------------|-------|---|--------------------|
| 0.5 | -261 | 3911 | 12.95 | 0.65 | 49 | 38.7 | 1.67 | 18.16 |
| 0.5 | 81 | 6780 | 12.35 | 0.66 | 47 | 119.0 | 0.545 | 4.38 |
| 0.7 | -117 | 7360 | 11.60 | 0.63 | 40 | 149.4 | 0.434 | 5.77 |
| 0.8 | -252 | 6372 | 11.23 | 0.61 | 33 | 116.6 | 0.556 | 10.41 |
| 0.8 | -117 | 8306 | 11.23 | 0.62 | 32 | 198.1 | 0.327 | 5.04 |
| 0.85 | -117 | 8765 | 10.80 | 0.60 | 37 | 229.6 | 0.282 | 4.66 |
| 0.9 | -117 | 9214 | 10.00 | 0.58 | 27 | 279.2 | 0.232 | 4.09 |

Test Results and Discussion

Experimental Data and Analysis Correlation

The experimental flutter results obtained in the 0.3-m TCT test are given in Table 3. For this flutter test, the model had free transition and was maintained at a near-zero degree angle of attack in a 1-g lift condition, i.e., aerodynamically supporting the wing weight. All of the experimental flutter conditions were obtained by peak-hold method extrapolations using measured subcritical response data. Experimental flutter conditions were determined for this model at $M=0.5$, 0.7, 0.8, 0.85, and 0.9. At $M=0.5$, flutter was obtained at Reynolds numbers of 4.4 and 18.4×10^6 . At $M=0.8$, flutter was obtained at Reynolds numbers of 5.0 and 10.4×10^6 . As shown in Fig. 16, the FAST analysis predicted the experimental flutter dynamic pressures rather well, with the analytical results ranging from up to 5% nonconservative at the lowest test Mach number to approximately 5% conservative at the high test Mach numbers. The Mach number effects on the flutter dynamic pressure also appear to be well predicted by the analysis.

Reynolds Number Effects

The effects of temperature and mass ratio variation between different data points have not been removed from the experimental data of Fig. 16. In an attempt to determine the Reynolds number effects on flutter, flutter points were obtained at two different Reynolds numbers at $M=0.5$ and 0.8. With Mach number held constant, the only test parameters that are believed to affect the flutter dynamic pressure are the differences in temperature, mass ratio, and Reynolds number. Analytical trends were used to adjust the flutter data for the differences in temperature and mass ratio so that Reynolds number becomes the sole parametric effect. The temperature adjustment was made by changing the experimental results by the percentage difference between the flutter dynamic pressure predicted by analysis at the given test temperature and at the reference temperature of 81°F using the trends shown in Fig. 15. In a similar manner, the experimental data were further adjusted for the effects of mass ratio. The resulting increments are shown in Fig. 17. The lines in Fig. 17 connecting the final adjusted data points show the variation in flutter dynamic pressure that is attributed solely to Reynolds number effects. At $M=0.5$, the flutter dynamic pressure decreased by 3.8% as the Reynolds number is increased from 4.4 to 18.4×10^6 . At $M=0.8$, the decrease is 2.3% for a Reynolds number increase from 5.0 to 10.4×10^6 . A linear extrapolation of the data at $M=0.8$ gives a 5.8% decrease in flutter dynamic pressure as Reynolds number is increased over the same range as at $M=0.5$ ($R=4.4\text{--}18.4 \times 10^6$). No hard flutter points were obtained as an absolute verification of the flutter conditions. Therefore, this Reynolds number effect could possibly fall within the scatter band of the subcritical response predictions, which was never established in the present test. Since the model

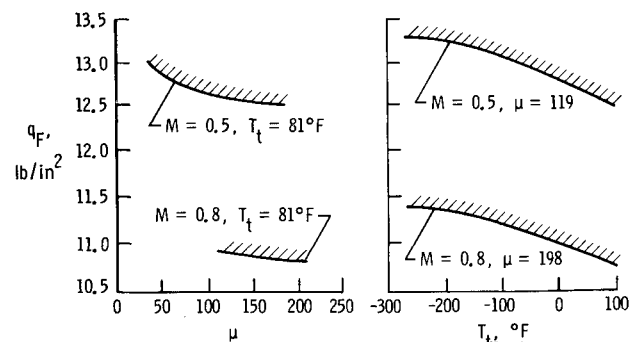


Fig. 15 Calculated mass ratio and temperature effects on flutter dynamic pressure.

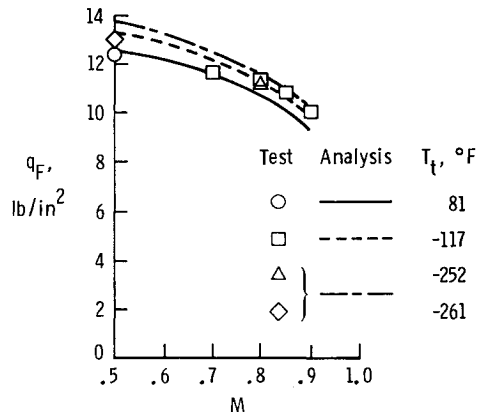


Fig. 16 Experimental and calculated flutter results.

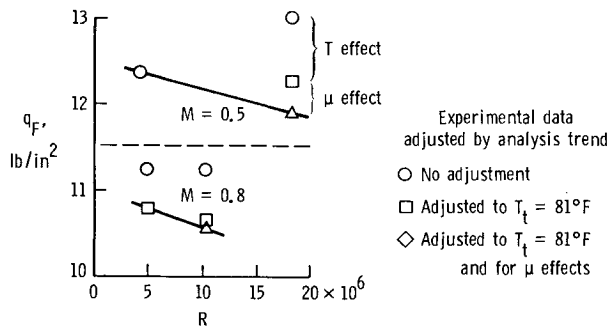


Fig. 17 Experimental effects of Reynolds number on q_F .

(symmetric airfoil) was tested at near-zero angle of attack, and at $M=0.5$ and 0.8 , strong shocks or separated flow would not be expected to play an important role. Therefore, the small Reynolds number effect on flutter is not surprising for this case. However, Reynolds number may have a more significant effect on flutter when separated flows or strong shocks are involved.

Conclusions

The feasibility of conducting flutter tests in cryogenic wind tunnels has been examined through this test. It has been found that flutter testing is possible in a cryogenic tunnel, but it must be regarded as a high-risk test and many concerns of model structural integrity must be addressed that are not usually considered in flutter tests in conventional wind tunnels. Flutter conditions were extrapolated during this test

using a subcritical response technique rather than by obtaining hard flutter points. The subcritical response technique gave consistent results throughout the temperature range of the tunnel. Several tunnel operating procedures for flutter testing in a cryogenic wind tunnel were evaluated. The operating procedure that is considered best is to increase the tunnel stagnation pressure while holding Mach number and stagnation temperature constant.

The important conclusions derived from this cryogenic flutter test are:

1) For a single test model, the effects of mass ratio and temperature cannot be experimentally separated from the effects of Reynolds number on flutter. Analytical trends were used to adjust experimental results to obtain the present Reynolds number effects on flutter.

2) The experimental effects of Reynolds number on the flutter characteristics of a rectangular planform, symmetrical airfoil shaped wing are small. Increasing Reynolds number from 5.0 to 20.0×10^6 decreased the adjusted flutter dynamic pressure by 4.0 – 6.5% at $M=0.5$ and 0.8 . This small percentage effect may possibly be within the scatter band of the experimental subcritical response predictions.

3) Temperature effects on flutter are appreciable because of changes in material stiffness properties.

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